

**UNIVERSITY OF LINCOLN
JOB DESCRIPTION**



JOB TITLE	Postdoctoral Research Associate in Agri-robotics – Fixed Term				
DEPARTMENT	School of Computer Science				
LOCATION	Brayford Campus / Riseholme Campus				
JOB NUMBER	COS780	GRADE	7	DATE	Sep 2020
REPORTS TO	Professor Marc Hanheide				

CONTEXT

The University of Lincoln is seeking to appoint a Postdoctoral Research Associate within Lincoln Centre for Autonomous Systems (L-CAS). This position is externally funded by the Innovate UK -funded ISCF TFP science and technology into practice: demonstration project ROBOT HIGHWAYS. The project aims to demonstrate the use of fleets of robotic and autonomous systems that pick, transport and pack soft fruits while gathering and process data to maximise yield and minimise waste, at scale. The University of Lincoln’s contributions to the project will include mobile robot autonomy; long-term fleet coordination; systems architecture development and system integration; learning and predicting activity patterns for better coordination; managing experimental work at test facilities on the University’s Riseholme Agricultural Campus as well as at commercial soft-fruit farms.

JOB PURPOSE

The Research Associate is responsible for conducting research on the project, as directed by the Principal Investigator, and is expected to operate with a significant degree of autonomy.

The post holder will investigate, develop, demonstrate and experimentally evaluate approaches to enable long term autonomy in robotic fleets, working with both simulated and physical robots. The research will consider direct practical applications to working in open fields, poly-tunnels and/or greenhouses at University’s Riseholme campus as well as commercial soft-fruit farms.

The post holder may be required to help supervise the work of more junior researchers.

KEY RESPONSIBILITIES

Literature Surveys
Undertake literature surveys and other investigations of the state-of -the-art, and prepare reports as required.
Programme of Research
Design and undertake programme of research under the direction of the Principal Investigator, demonstrating a significant level of autonomy. Lead in the production of high-quality research outputs, including reports, papers and other publications of national/international standing.
Project Management
Perform project management activities, planning, scheduling, monitoring and reporting on progress of research projects.
Liaison and Networking
Identify and liaise with internal and external collaborators, and with colleagues in the Department, maintaining positive and effective working relationships.
Internal Research Activities
Participate in and help to organise internal research activities, including seminars, research meetings and conferences.
Continuous Professional Development
Undertake continuous professional development activities.
Grant Applications
Contribute to the production of grant applications.
Teaching Support
Aid in the supervision of postgraduate research students.

In addition to the above, undertake such duties as may reasonably be requested and that are commensurate with the nature and grade of the post.

ADDITIONAL INFORMATION

Scope and dimensions of the role
The postholder will be expected to design, conduct and manage original research in the area of the project, which encompasses underpinning research topics including (but not limited to): Agri-robotics; AI methods for long-term robot autonomy; Machine learning for autonomous robots; Human aware robot navigation; Coordination strategies for robotic fleets; Systems integration, including ROS. Candidates should have, or expect to soon obtain, a PhD in a relevant area and hands-on experience with mobile ground robots. They must have excellent mathematical and coding skills

(C++/Python, ROS). Specific experience in the agriculture domain is preferred but not required. Postdoctoral positions will be fixed term for initially 2 years (with possible extension). The role offers the opportunity to engage in collaboration within an ambitious team, to work closely with Lincoln Agri-Robotics (LAR), the world's first global centre of excellence in agricultural robotics, to work with state-of-the-art robotic hardware and software, and to benefit from excellent support to produce and disseminate original research contributions at the leading international conferences and journals. The post holder will be in a unique position to implement approaches that will be used in commercial agricultural farms.

Key working relationships / networks	
Internal	External
Principal Investigator Co-Investigators Head of Research Centre Head of School Other research and academic staff within the school	Research collaborators Sponsors and clients

PERSON SPECIFICATION

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Selection Criteria	Essential (E) or Desirable (D)	Where Evidenced Application (A) Interview (I) Presentation (P) References (R)
Qualifications:		
PhD or equivalent (good candidates may be accepted with a PhD pending, subject to publication record)	E	A
Extensive knowledge specific to project/area	E	A/I
Experience:		
Extensive experience of relevant research methods	E	A/I
Authorship of research outputs of national/international standing	E	A/I
Experience of research in specific project area	E	A/I
Skills and Knowledge:		
Ability to design, conduct and project manage original research in the subject area	E	A/I
Excellent written communication, including the ability to write reports and research outputs	E	A/I
Ability to prioritise own workload and work to specified deadlines under pressure	E	A/I
Ability to communicate complex subjects orally	E	A/I
Skills specific to project/area	E	A/I
Competencies and Personal Attributes:		
Flexible approach to workload	E	I
Ability to work on own and as part of a team	E	I
Enthusiasm and commitment	E	I
Business Requirements:		
Travel between sites as appropriate	E	I

Essential Requirements are those, without which, a candidate would not be able to do the job. Desirable Requirements are those which would be useful for the post holder to possess and will be considered when more than one applicant meets the essential requirements.

Author	GD	HRBA	
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